

Tech Sheet 2025-01-28

G series





Helical gearmotor G MR 2I 63 UP2A - 24 x 200 - 13,1 B3 HB3 90S 4 230.400-50 B5 ,VA





Configured product

Designation

G MR 2I 63 UP2A - 24 x 200 - 13,1 B3 HB3 90S 4 230.400-50 B5 ,VA

Helical gearmotor G series
Input speed n ₁ 1 420 min ⁻¹
Coupled with motor
Mounting position B3

Accessories

Standard low speed shaft [AN1]
Reaction bolt using disc springs [B1]

Helical gearmotor - Technical data

Transmission ratio	13.1
Effective ratio <i>i</i> _{EFF}	13.07
Output speed n_2	[min ⁻¹] 108.67
Input speed n_1	[min ⁻¹] 1 420
Applied power P ₁	[hp] 0
Output torque M ₂	[Lb-in] 821.58
Service factor s_f (installed power)	3.329
Nominal efficiency η	0.96
Gearmotor mass (without motor)	[lb] 41.67
Moment of inertia (of mass) J ₁	[lb ft ²] 0.0024
Sound levels (to ISO/CD 8579, tolerance +3 dB(A)) sound power level L _{WA} sound pressure level L _{pA}	[dB(A)] 78 [dB(A)] 69
Angular backlash at a distance of 3.28 [ft] from the low speed shaft centre min max min max	[rad] 0.0028 [rad] 0.0056 [arcmin] 9.6 [arcmin] 19
Torsional stiffness in condition of nominal load	[lb in / arcmin] 159.31



Lubrication

[gal] 0.24
[cSt] 150 220
220
220

Overall guide to oil-change ir	nterval (not according ATEX directive)
	Oil change interval [b]

Oil temperature[° F]	Oil change interval [h]				
	mineral oil	synthetic oil			
≤ 149	8 000	25 000			
149 ÷ 176	4 000	18 000			
176 ÷ 203	2 000	12 500			
203 ÷ 230	-	9 000			

Nominal data

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Nominal input power P _{N1}	[hp] 4.9
Nominal output power P _{N2}	[hp] 4.7
Nominal thermal power P _{TN} @68°	[hp] 13.41
Nominal output torque M_{N2}	[Lb-in] 2 734.88
Maximum output torque M _{2 MAX}	[Lb-in] 4 372.27



Main dimensions [mm] (for accessories, see following pages) 63 - 63 -58.5h12 - 62h11-113 80h11 287 3 0 æ 80h11 100 ø30H7 ø80h6 ø120 -@176 102 80h11 ⊕ ¢ 14 ø11.5 90 102 114 143 440 ¢ Φ Ο -334 100 ø200 ~141 Information Screws UNI 5737: M 10 x 35 Bolts UNI 5588: M 10 Product liability, application considerations The customer is responsible for the correct selection and application of product in view of its industrial and/or commercial needs, unless the use has been recommended by technical qualified personnel of Rossi, who were duly informed about customer's application purposes. In this case all the necessary data required for the selection shall be communicated exactly and in writing by the customer, stated in the order and confirmed by Rossi. The customer is always responsible for the safety of product applications. Every care has been taken in the drawing up of the catalog to ensure the accuracy of the information contained in this publication, however Rossi can accept no responsibility for any errors, omissions or outdated data. Due to the constant evolution of the state of the art, Rossi reserves the right to make any modification whenever to this publication contents. The responsibility for the product selection is of the customer, excluding different agreements duly legalized in writing and undersigned by the parties.



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Reaction bolt using disc springs - B1

IMPORTANT: When shaft mounted, the gearmotor must be supported both axially and radially (even for mounting positions B3 ... B8) by the shaft end of driven machine, as well as anchored against rotation only, by means of a reaction having freedom of axial movement and suffi cient clearance in its couplings to permit minor oscillations - always in evidence - without provoking dangerous overloads on the gearmotor. Lubricate with proper products the hinges and the parts subject to sliding; when tightening the screws it is recommended to apply locking adhesives type LOCTITE 601.





Configured motor

Designation

HB3 90S 4 230.400-50 B5 ,VA



Motor catalog TX - Erp Pn 1.1 kW (1.5 hp) Motor specifications

> 5 voltage values stated on nameplate: 220.380 @50Hz
> 230.400 @50Hz
> 240.415 @50Hz
> 265.460 @60Hz
> 277.480 @60Hz

Motor mounting position (IM) B5

Axial independ. cooling fan VA [,VA]

Electric motor technical data TX catalog

Туре	HB3 90 S 4
Size	90
Poles	4
Coupling dimensions Ø D x E - Ø P	Ø24 x 50 Ø200
Power supply	[V - Hz] 230.400 - 50
Nominal input power P _{N1}	[hp] 1.5
Nominal speed n _N	[min ⁻¹] 1 420
Motor mass	[lb] 41
Directive	Motor ErP
Efficiency class	IE3
Power factor cosφ	0.8
Moment of inertia J ₀	[lb ft ²] 0 014.0104
Overtemperature class	В
Insulation class	F
Protection	IP 54
Type of duty	S1
Synchronous speed	[min ⁻¹] 1 500
Efficiency	
100 %	84.10
75 %	84.80

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50 %

83.60

Nominal data

Nominal torque M _N	[Lb-in] 65.50
Nominal starting torque M _s / M _n	3.00
Maximum torque M_{MAX} / M _n	3.50
Starting current ratio <i>i_s / i_n</i>	6.40
Rated current In @230 [V]	[A] 4.20
Rated current In @400 [V]	[A] 2.40

Construction features

Motor size	Bearing D-E	Bearing N-D-E	Housing	Flange B5	End-shield N-D-E	Terminal box cover	Seal rings D-E	Terminal block (4)	Cable glands	Fan cover	Cooling fan
90 S	6205 2Z	6205 2Z	LL	LL	LL	LL	25 × 46 × 7	M5	2 × M16 + 2 × M25	Painted sheet	Plastic

LL = Light alloy

(4) Terminal block with 6 terminals for cable terminal connection

Axial independent cooling fan

Motor				Independent cooling fan nameplate				Independer cooling	nt
size	V	Hz	V	Hz	W	А	Kg	type	code
90	Δ220 Y380	50	230	50/60	45 / 39	0.31 / 0.25	0.9	single phase	,VA
90	Δ230 Υ400	50	230	50/60	45 / 39	0.31 / 0.25	0.9	single phase	,VA
90	∆240 Y415	50	230	50/60	45 / 39	0.31 / 0.25	0.9	single phase	,VA
90	Δ265 Y460	60	230	50/60	45 / 39	0.31 / 0.25	0.9	single phase	,VA
90	Δ277 Y480	60	230	50/60	45 / 39	0.31 / 0.25	0.9	single phase	,VA



Motor main dimensions [mm]

